

Surveying the world of tomorrow –

Helsinki Finland 29 May - 2 June 2017

From digitalisation to augmented reality

Introduction

- Mapping of power lines for cadastre use
- LiDAR data
- Fusion of different methods for data extraction
- Problems with methods
- Obtained valid and accurate data





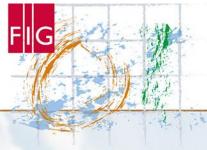












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Workflow



Automatic classification

Semi-automatic classification 2D and 3D vectorization

Longitudinal profiles and cadastre maps





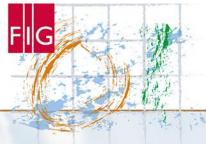










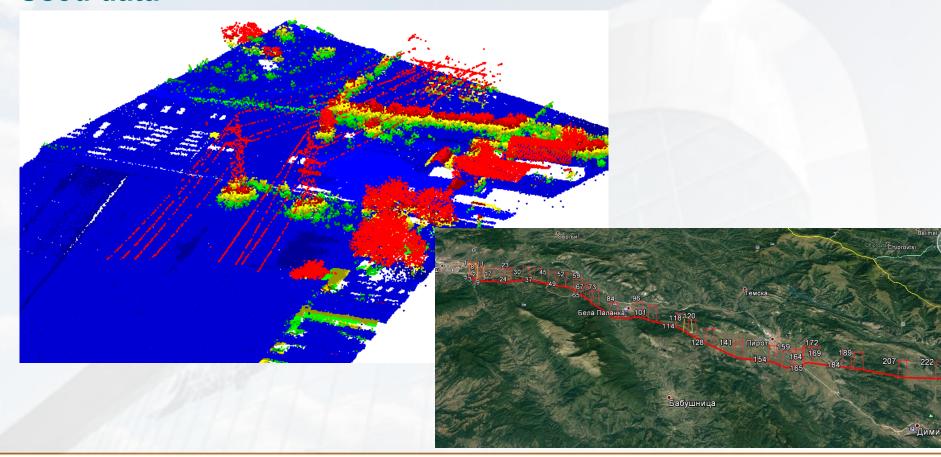


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Used data







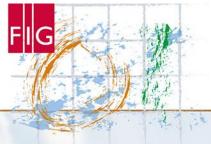




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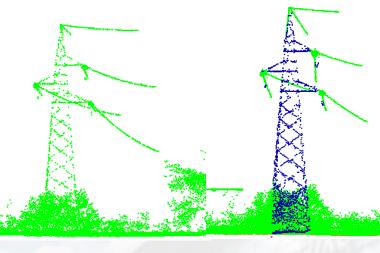
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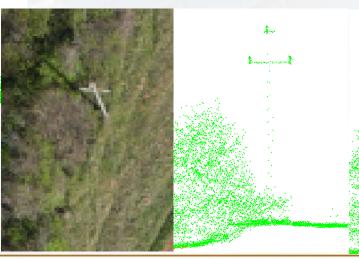
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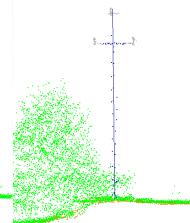
Misclassified points

misclassified points of pole



points close to vegetation that belongs to pole









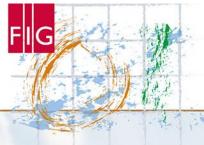




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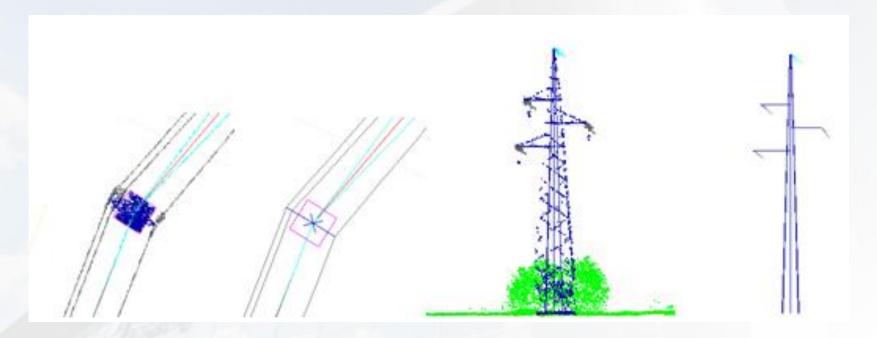


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2D and 3D Vectorizaton of poles







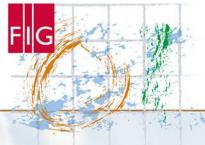










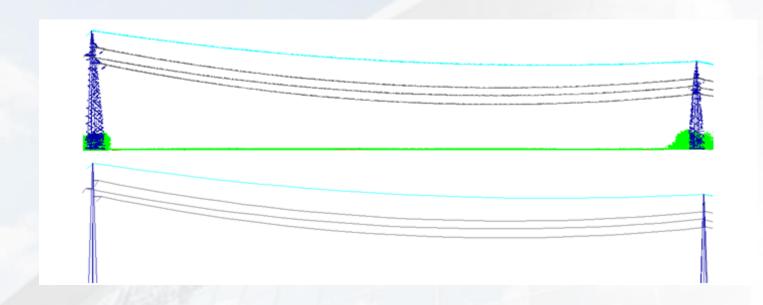


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3D Vectorizaton of poles and wires







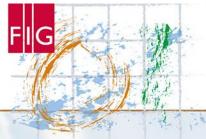










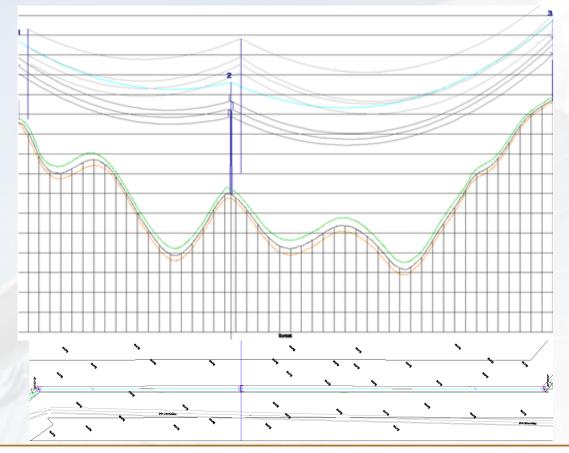


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Longitudinal profile and cadastre map







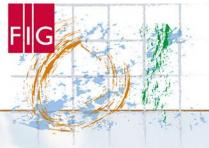












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Conclusion

- Valid informations for cadastre
- Precise i accurate data used in Electricity distribution infrastructure

Future work:

- Will be focused on finding the ideal solution for semi-automatic classification and vectorization.
- -Solution should be basic automatic classification that would classify much more point classes that automatic classification could not classify.





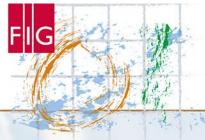












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Past

Future is here

