Position Determination **Technologies**

- GNSS
- Proximity / beacons
- Wave-based range PDT
- Autonomous / "dead reckoning"
- ◆ Mobile Telephony
- Augmentations / integrated systems

Because GPS is not 100% available...

(1) GPS/GNSS

Reference stations or infrastructure:



- ♦ Global frame networks, e.g. IGS
- ◆ Local CORS for relative positioning

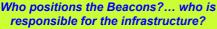
GPS reference stations now recognised as Survey/Geodetic infrastructure...



(2) 'Proximity' or 'Beacon' Systems

Issues: range, cost, installed infrastructure, non-global, etc.

- ♦ Many varieties of proximity sensors ... optical, infrared, RF, acoustic, etc.
- Passive (CCTV), 'transaction' (ATMs, credit cards), 'entry' (swipe cards), etc...
- Primarily for indoor applications, but some vehicle systems (transponders, optical, etc) ...
- Track/tag people, animals, vehicles & assets ..
- New 'lease of life' with short-range wireless communications technologies such as Bluetooth, UWB, ZigBee, WiFi, etc., and barcode replacement technologies such as RFID ... also "Cell-ID" (see mobilephone systems) ...





All require "infrastructure

reference stations"...

connect to the reference

frame

(3) Wave-based Range PDTs

Issues: range, cost, installed infrastructure, non-global, etc.

- Many varieties of wave sensors can allow signal strength or timing measurements to be made ... optical, infrared, RF, acoustic ...
- Range (distance) derived from SS or TOA ...
- Need multiple transmitters or "access points" ...
- Potentially can be long-range (even overthe-horizon), and high accuracy ...
- Range of accuracies from cms to dekametres like GPS
- Using installed infrastructure for short-range wireless communications technologies such as Bluetooth, UWB, ZigBee, WiFi, etc., is clever ...

Who is responsible for the infrastructure?











Know where you are, and direction/speed/distance -> calc position

- ♦ Requires no signal transmission ...
- Works anywhere, totally autonomous ... hence no infrastructure
- Low-cost MEMS or expensive INS ...
- Compass, gyros, accelerometers, odometers, pedometers, barometers ...
- However subject to (significant) drift error ...
- Need regular calibration against datum.
- Often used in combination with GPS, e.g. GPS/DR & GPS/INS







